The pre-collision system detects pedestrians based on the size, profile, and motion of a detected object. However, a pedestrian may not be detected depending on the surrounding brightness and the motion, posture, and angle of the detected object, preventing the system from operating properly. ( $\rightarrow$ P. 247)



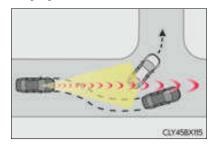
\*4: Depending on the region in which the vehicle was sold, the pedestrian detection function may not be available.

## ■ Cancelation of the pre-collision braking \*3

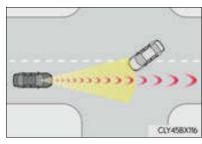
- If either of the following occur while the pre-collision braking function is operating, it will be canceled:
  - The accelerator pedal is depressed strongly.
  - The steering wheel is turned sharply or abruptly.
- If the vehicle is stopped by the operation of the pre-collision braking function, the operation of the pre-collision braking function will be canceled after the vehicle has been stopped for approximately 2 seconds.
- \*3: Depending on the region in which the vehicle was sold, the pre-collision braking function may not be available.

## ■ Conditions under which the system may operate even if there is no possibility of a collision

- In some situations such as the following, the system may determine that there is a possibility of a frontal collision and operate.
  - When passing a vehicle or pedestrian\*4
  - · When changing lanes while overtaking a preceding vehicle
  - When overtaking a preceding vehicle that is changing lanes
  - When overtaking a preceding vehicle that is making a left/right turn

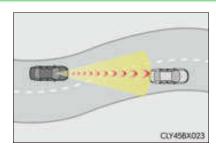


• When passing a vehicle in an oncoming lane that is stopped to make a right/left turn

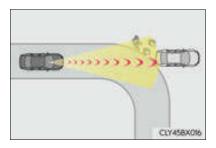


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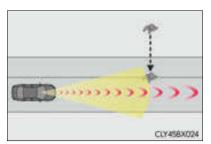
 When driving on a road where relative location to vehicle ahead in an adjacent lane may change, such as on a winding road



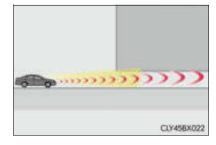
- When a preceding vehicle suddenly decelerates
- If the front of the vehicle is raised or lowered, such as when the road surface is uneven or undulating
- When approaching objects on the roadside, such as guardrails, utility poles, trees, or walls
- When there is a vehicle, pedestrian\*4, or object by the roadside at the entrance of a curve

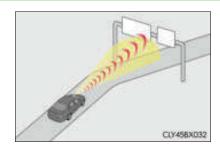


- When driving on a narrow path surrounded by a structure, such as in a tunnel or on an iron bridge
- When there is a metal object (manhole cover, steel plate, etc.), steps, or a protrusion on the road surface or roadside
- When a crossing pedestrian approaches very close to the vehicle\*4

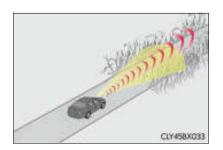


 When passing through a place with a low structure above the road (low ceiling, traffic sign, etc.)





- When rapidly closing on an electric toll gate barrier, parking area barrier, or other barrier that opens and closes
- · When using an automatic car wash
- When driving through or under objects that may contact the vehicle, such as thick grass, tree branches, or a banner



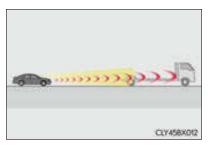
- · When the vehicle is hit by water, snow, dust, etc. from a vehicle ahead
- · When driving through steam or smoke
- When there are patterns or paint on the road or a wall that may be mistaken for a vehicle or pedestrian\*4
- When driving near an object that reflects radio waves, such as a large truck or quardrail
- When driving near a TV tower, broadcasting station, electric power plant, or other location where strong radio waves or electrical noise may be present
- \*4: Depending on the region in which the vehicle was sold, the pedestrian detection function may not be available.

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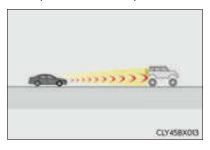
Driving

## ■ Situations in which the system may not operate properly

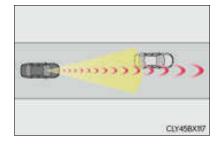
- In some situations such as the following, a vehicle may not be detected by the radar sensor and camera sensor, preventing the system from operating properly:
  - If an oncoming vehicle is approaching your vehicle
  - If a vehicle ahead is a motorcycle or bicycle
  - When approaching the side or front of a vehicle
  - If a preceding vehicle has a small rear end, such as an unloaded truck
  - If a preceding vehicle has a low rear end, such as a low bed trailer



- If a vehicle ahead is carrying a load which protrudes past its rear bumper
- If a vehicle ahead has extremely high ground clearance



- If a vehicle ahead is irregularly shaped, such as a tractor or side car
- If the sun or other light is shining directly on a vehicle ahead
- If a vehicle cuts in front of your vehicle or emerges from beside a vehicle
- If a vehicle ahead makes an abrupt maneuver (such as sudden swerving, acceleration or deceleration)
- When suddenly cutting behind a preceding vehicle
- When a vehicle ahead is not directly in front of your vehicle



- When driving in inclement weather such as heavy rain, fog, snow or a sandstorm
- · When the vehicle is hit by water, snow, dust, etc. from a vehicle ahead
- · When driving through steam or smoke
- When driving in a place where the surrounding brightness changes suddenly, such as at the entrance or exit of a tunnel
- When a very bright light, such as the sun or the headlights of oncoming traffic, shines directly into the camera sensor
- When the surrounding area is dim, such as at dawn or dusk, or while at night or in a tunnel

- After the engine has started the vehicle has not been driven for a certain amount of time
- While making a left/right turn and for a few seconds after making a left/right turn
- While driving on a curve and for a few seconds after driving on a curve
- If your vehicle is skidding
- · If the front of the vehicle is raised or lowered
- If the wheels are misaligned
- If a wiper blade is blocking the camera sensor
- The vehicle is wobbling.
- · The vehicle is being driven at extremely high speeds.
- When driving on a hill
- If the radar sensor or camera sensor is misaligned
- In some situations such as the following, sufficient braking force may not be obtained, preventing the system from performing properly:
  - If the braking functions cannot operate to their full extent, such as when the brake parts are extremely cold, extremely hot, or wet
  - If the vehicle is not properly maintained (brakes or tires are excessively worn, improper tire inflation pressure, etc.)
  - When the vehicle is being driven on a gravel road or other slippery surface
- Some pedestrians such as the following may not be detected by the radar sensor and camera sensor, preventing the system from operating properly\*4:
  - Pedestrians shorter than approximately 3.2 ft. (1 m) or taller than approximately  $6.5 \, \text{ft.} \, (2 \, \text{m})$
  - Pedestrians wearing oversized clothing (a rain coat, long skirt, etc.), making their silhouette obscure
  - Pedestrians who are carrying large baggage, holding an umbrella, etc., hiding part
    of their body
  - Pedestrians who are bending forward or squatting
  - Pedestrians who are pushing a stroller, wheelchair, bicycle or other vehicle
  - Groups of pedestrians which are close together
  - Pedestrians who are wearing white and look extremely bright
  - Pedestrians in the dark, such as at night or while in a tunnel
  - Pedestrians whose clothing appears to be nearly the same color or brightness as their surroundings
  - Pedestrians near walls, fences, guardrails, or large objects
  - Pedestrians who are on a metal object (manhole cover, steel plate, etc.) on the road
  - Pedestrians who are walking fast
  - Pedestrians who are changing speed abruptly
  - Pedestrians running out from behind a vehicle or a large object
  - Pedestrians who are extremely close to the side of the vehicle (outside rear view mirror, etc.)
- \*4: Depending on the region in which the vehicle was sold, the pedestrian detection function may not be available.

4

Driving